

Installation and Service Manual Besam Revolving Door

RD3/RD4, RD3A1/RD4A1, RD4A2



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The following pages have been revised:

| Page | Revision |
|------|---|
| — | This is the first version of Installation and Service Manual, No. 1004466-EI-2.0, |
| | issued 2008-02-19, for Besam 3 and 4 winged Resolving Doors. |

2.1 Important notice

To avoid bodily injury, material damage and malfunction of the product, the instructions contained in this manual must be strictly observed during installation, adjustment, repairs and service, etc. Only Besam-trained technicians should be allowed to carry out these operations. Save these instructions.

2.2 Radio and television reception

This equipment generates and uses radio frequency energy and if not installed and used properly, that is, in strict accordance with the manufacturer's instructions, it may cause interference to radio, television reception or other radio frequency type systems. It has been designed to comply with the emission limits in accordance with EN 61000-6-3 (US market FCC Part 15), which are designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Re-orient the receiving antenna.
- Relocate the receiver with respect to the equipment.
- Move the receiver away from the equipment.
- Plug the receiver into a different outlet so that equipment and receiver are on different branch circuits.
- Check that protective earth (PE) is connected.

If necessary, the user should consult the dealer or an experienced radio/television technician for additional suggestions.

2.3 Environment

This operator is equipped with electronics and may also be equipped with batteries containing materials which are hazardous to the environment. Remove this material from the operator before it is scrapped and make sure that it is disposed of safely along with the packaging. This manual contains the necessary details and instructions for the installation, maintenance and service of Besam 3 and 4 winged Revolving Doors.

The Besam Revolving Doors are easy to install for both new construction and retrofit applications and they can be adapted to a wide range of door requirements. A Besam Revolving Door shall always be equipped with a safety system that suits the application. Besam Revolving Doors can be combined with the full range of Besam safety systems.

Each installation is unique and must therefore be equipped and adjusted for the application-relevant safey requirements, just like maintenance must be performed as specified for the selected product.

Technical specifications

- Power supply: 100 240 V, 50 60 Hz
- Power consumption: 400 W
- Lighting: 12 V, 120 W
- Mains fuse: 10 A

Installation

5.1 Pre-installation check

5.1.1 Mains supply



EAB094

| | Description |
|---|---|
| А | 100/115/230V, 50/60Hz, 10A, mains fuse max 10A |
| | Power consumption 600W |
| В | Fuse |
| С | Main switch (by others) |
| | An all pole mains switch having a contact separation of, at least, 3 mm shall |
| | be incorporated in the mains wiring in accordance with national wiring regu- |
| | lations. |
| D | Power supply for spotlights (option). Mains fuse 10A. |

5.2 Floor surface



| Spot | Value | 0-spot value | Difference (Max +/- 3mm) |
|------|-------|--------------|-----------------------------|
| 1 | | | |
| 2 | | | |
| 3 | | | |
| 4 | | | |
| 5 | | | |
| 6 | | | |
| 7 | | | |
| 8 | | | |
| 9 | | | |
| 10 | | | |
| 11 | | | |
| 12 | | | |
| 13 | | | |

5.2.1 Mark up



Mark line A. Line A is the centre line of the door between the adjacent walls.

Mark the centre point of the door (B) along line A.

Mark circle C. Use the centre pivot plate as guide.

Mark circle D. This circle is the inside diameter of the fixing rails. For radius, see table.

If a ground ring is used, use the centre of the ground ring as a guide for line A and centre B



| Door type | Nominal R Frame | Nominal R Slim |
|-----------|-----------------|----------------|
| RD3/4-18 | 906 | 904 |
| RD3/4-21 | 1056 | 1054 |
| RD3/4-24 | 1206 | 1204 |
| RD3/4-27 | 1356 | 1354 |
| RD3/4-30 | 1506 | 1504 |
| RD3/4-36 | 1806 | 1804 |

Max. deviation 1 mm

5.2.2 Fit the fixing rail and the centre pivot plate



| Spot | Value | 0-spot value | Difference Max. +/- 0.5 mm |
|------|-------|--------------|-------------------------------|
| 1 | | | |
| 2 | | | |
| 3 | | | |
| 4 | | | |
| 5 | | | |
| 6 | | | |
| 7 | | | |
| 8 | | | |
| 9 | | | |
| 10 | | | |
| 12 | | | |

5.3 Outer walls

5.3.1 Outer wall sections





RTS ST 5.5x22

5.3.2 Wall ring Frame





A RTS ST 6.3x32. BRB 6.4

В

MC6S 8x60

5.3.3 Wall ring Slim





MC6S 8x25

5.3.4 Brackets







MC6S 8x25 Do not tighten the bolts. The brackets close to the openings shall be located above the wall sections.

Brackets



| Item | Used where? |
|------|--|
| Α | Door without NCD. |
| | Fascia height 200 - 1250 mm. |
| В | External half of doors with NCD. Fascia height 200 - 210 mm. |
| С | External half of doors with NCD. Fascia height 211 - 280 mm. |
| D | External half of doors with NCD. Fascia height 281 - 1250 mm. |

5.4 Centre beam





MC6S 8x50 Do not tighten the bolts.

5.5 Drive unit





MC6S 8x16 M6M M8



Level the drive unit with the adjustment screws on the centre beam fixing brackets.

5.6 Top ring



5.7 Night closing doors (NCD)

5.7.1 Support beam



MC6S 8x25

Fascia height 200 - 210 mm





Fascia height 211 - 280 mm





Fascia height 281 - 1250 mm





5.7.2 Carriage wheel fittings



5.7.3 Floor guide



MF6S 6x20



5.7.4 Door leaves

5.7.5 Slam posts





RXS ST 3.5x13

5.7.6 Door stop



STI

5.7.7 Automatic NSD



5.8 Electrical installation

5.8.1 Connection box



MC6S 8x25 M6M M8 Fix the mains connection box firmly to the centre beam fixing bracket.



5.8.2 Control box





A single motor shall be connected to connection M1.

5.8.4 Cabling



5.9 Centre shaft



Make sure that the hole for the lock lines up with one of the door leaves.



Grease the teeth on the cogwheel and the area in front of the hole for the lock



Tighten the centre beam bolts.

5.10 Adjustment of the motor assembly



Put the two cup shaped washers in place (note the orientation). Tighten the first nut with your fingers plus a 1/2 turn extra. Secure the first nut with a second nut.

5.11 Door leaves



Put the door leaf on the bottom flange of the centre shaft.

Raise the door leaf.

Fix the door leaf to the top flange of the centre shaft with the special bolts (A). Secure the bolts with Loctite 638.

5.11.1 RD Slim centerless



Secure the two top screws (A) on the door leaves facing outwards with 5.3x26 mm pins (B).

5.11.2 Adjustment of emergency break-out kit



Put the door leaf in app. 30° break-out position (see illustration above).

Tighten the spring marked A with the screw marked B equally at the top and the bottom. The door leaf shall be able to take a load of 60 kg (F).

Close the door leaf. Check the break-out force (<150N) and adjust if necessary with the screw marked B equally at the top and the bottom.

Note: After making this adjustment re-check that the door leaf can still take the load of 60 kg.

If the door is not equipped with the emergency break-out kit, tighten the stop screw marked C on the side to which the door leaf shall be broken out to and remove the other one. The door leaves shall be broken out in the opposite to the direction of rotation (backwards).





Adjust the height level of the lifting fork to make the distance between the lifting fork and the groove in the locking ring equal by adjusting the nuts (A).

Locking ring

5.12 Centre plates





M6M M6.



Adjust the internal height to the centre plates by putting shims between the drive unit and the centre plates.

5.13 Ceiling



Put all parts of the ceiling in place using the edge strips. Use the 100 mm edge strips for the inspection hatches and the 300 mm edge strips for the others. The inspection hatches (marked A) shall be towards the inside of the building.

Adjust and get even joints.

Secure with fixing angle (B)

To prevent damage during operation or service, secure one of the inspections hatches also with fixing angle (B).

Use a credit card to lock and unlock the inspection hatches.



5.14 Fascia



5.15 Dust protection roof





2 No. A = 4 No. screws MC6S 8x25 Push the parts together using the guiding tongues. Screw the dust roof to the can-

opy ring (ST 4.2x32). Note! Roof load: 0 kg

(if not reinforced)


Signage and Safety equipment



- A Product label: Mandatory
- (B) Emergency break-out: Mandatory, if applicable
- © No entry, identifying one-way traffic: Mandatory in GB and US, if applicable
- D Emergency open push button, if applicable
- (E) Programme selector PCD
- (F) Emergency stop push button, mandatory
- G Push button for disabled
- (H) Besam door sticker: Mandatory, if applicable (applied to both sides of the door). To be used if there is no other signs on a full-glass door.
- Supervision of child: Mandatory, if applicable (applied to both sides of the door). To be placed on entrances where the risk analysis shows majority use by children, elderly and disabled.
- K Automatic door: Only mandatory in GB
- (L) Keep clear: Only mandatory in GB
- \bigcirc Push buttons inside door

6

Control system

7.1 Identification



| Item | Description |
|------|------------------------------------|
| А | IOA 1 terminals |
| В | IOA 2 terminals |
| С | IOB terminals (Access doors only). |
| D | MPU Main processing unit |
| Е | Evacuation push button |
| F | Emergency stop push buttons (2) |
| G | DPC-board |

7.2 Status codes



Diagnostic out-put

It is possible to monitor the system by looking at the red and yellow out-put LED's on the control unit CDC.

| | Cause | I/OA-1 (red LED) | I/OA-2 (yellow LED) |
|-------|----------------------------|------------------|---------------------|
| 10 | Safety stop | Fixed light | |
| 20 | Emergency stop | | Fixed light |
| 30 | Blocked door | Fixed light | Fixed light |
| 21-22 | Vertical sensors activated | Flashing light | |
| C2 | BOK magnet | | Flashing light |
| 9A | Overheat | Flashing light | Flashing light |
| 11 | Electromechanical lock | Fixed light | Flashing light |
| 06-07 | Encoder error | Flashing light | Fixed light |

7.3 DPC-board



| Item | Description |
|------|--------------------------------------|
| 1 | Connector, to MPU-board (J 10) |
| 2 | LED green, -12V |
| 3 | LED green, +5V |
| 4 | LED green, +12V |
| 5 | LED green, +24V |
| 6 | LED green, +42V |
| 7 | Connector, evacuate function (J11) |
| 8 | Connector, -12V (J 2) |
| 9 | Connector, 0V (J 2) |
| 10 | Connector, +5V (J 2) |
| 11 | Connector, +12V (J 2) |
| 12 | Connector, +24V (J 2) |
| 13 | Connector, motor M1 (J 4) |
| 14 | Earth |
| 15 | Connector, motor M2 (J 8) |
| 16 | Connector, emergency stop (J 15) |
| 17 | Fuse, battery 16 AT (slow) (F 3) |
| 18 | Connector, battery in (J 13) |
| 19 | Fuse, mains power 10 AT (slow) (F 2) |
| 20 | Fuse, mains power 10 AT (slow) (F 1) |
| 21 | Mains power (J 1) |
| 22 | Power outlet for lighting (J 9) |
| 23 | LED red, thermal overload indicator |
| 24 | LED yellow, mains power indicator |

7.4 Main processing unit, MPU



| Item | Description |
|------|---------------------------------------|
| А | Connector, PCD B (J 7) |
| В | Connector, PCD A (J 6) |
| С | Connector, COM port (J 5) |
| D | Programming connector (J 11) |
| E | Ram memory and battery backup |
| F | Flash memory |
| G | Main processor CPU |
| Η | LED3, indicator 24V (PCD) |
| J | LED2, indicator 12V Logic |
| K | LED1, indicator 5V Logic |
| L | Reset button |
| М | Connector, power from DPC-board (J 1) |
| Ν | Connector, signals to DPC-board (J 4) |
| 0 | Connector, to IOA 1 (J 9) |
| Р | Connector, to IOA 2 (J 10) |
| R | LED Error frequent reset. |
| S | LED Watchdog on in normal condition |

7.5 IOA 1-board

| 5 | | Conn | Term | | Description RD | Description RD Access |
|--|---|------|----------|---------|--------------------------------|------------------------|
| 3 | | J12 | 1 | + | Encoder | |
| 4 | | | 2 | IN | Encoder 0-puls | |
| 5 | | | 3 | IN | Encoder A-puls | |
| <u>ه</u> | | | 4 | IN | Encoder B-puls | |
| ∠ | | | 5 | | * | |
| 8 | | J13 | 6 | + | Vertical sensor PDR1 (inside) | |
| 0 0 | | | 7 | IN | | |
| 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | | | 8 | - | | |
| 7 | | J14 | 9 | + | Vertical sensor PDR2 (outside) | |
| 3 1 | | | 10 | IN | | |
| 14 | | | 11 | - | 1 | |
| 15 | | J15 | 12 | IN | Not used | System OK inner |
| J 16 | | | 13 | | 1 | |
| 3 17 | | | 14 | IN | Not used | System OK outer |
| 9 18 | | | 15 | | 1 | |
| - | - | | 16 | IN | Slow drive | • |
| 1 20 J 16 | | | 17 | |] | |
| | | | 18 | IN | Stop drive | |
| 25 2 | | | 19 | | | |
| | | J16 | 20 | IN | Not used | Freewheel released |
| 27 17 | | | 21 | | | |
| 9 28 | | J17 | 24 | OUT | Safety loop out | External jumper |
| 0 36 | | | 25 | (IN) | | |
| en la construction de la constru | | | 26 | | | External jumper |
| | | | 27 | (IN) | | |
| | | | 28 | | Safety loop code 10 | |
| | | | 29 | IN | | |
| 31 | | | 30 | | Not used | |
| 18 | | J18 | 31 | IN | Not used | Freewheel command |
| 4 133 | | | 32 | | | |
| 5 3 | | | 33 | IN | Not used | Fire alert |
| 36.3 | | | 34 | | | |
| 37 | | J19 | 35 | IN | EI-mech. lock locked | Freewheel motor closed |
| <u>8</u> ~ | | | 36 | | | |
| 39 | | | 3/ | IN | EI-mech. lock open | Freewheel motor open |
| 40 | | | 38 | | El mach lock mater | Frankhad motor |
| 2 41 | | | 39 | | EI-mech. lock motor | Freewheet motor |
| 34 | | 120 | 40 | | Not used | |
| J 2(| | J20 | 41 | | | |
| 45 4 | | | 42 | | Not used | Security level inner |
| 46 | | | +3 // | + IN | | |
| 47 | | | 45 | | PDR test | 1 |
| 48 1 | | | 46 | OUT | | |
| 49 | | J21 | 47 | | Not to be used | |
| 22 | | 021 | 48 | | | |
| 2 51 J | | J22 | 49 | | Error signal 1 | |
| 22 | | | 50 | OUT | | |
| 0 | | | 51 | OUT | Door status | |
| Z | | | 52 | | 1 | |
| 14 | | L | 1 | 1 | 1 | |

EAA952

Digital inputs. IOA 1-board

Terminal 2. 0-pulse Incremental encoder 0-pulse input.

Terminal 3. A-pulse Incremental encoder A-pulse input.

Terminal 4. B-pulse Incremental encoder B-pulse input.

Terminal 7. Vertical sensor PDR 1, inside The door is stopped when input is activated by presence in the safety zone.

Terminal 10. PDR 2, outside The door is stopped when input is activated by presence in the safety zone.

Terminal 16. Slow

Door speed is reduced to "Creep speed" when input is activated. "Creep speed" is held until 1 s after input deactivation.

Terminal 18. Stop

The door is stopped when input is activated. The door starts again 1 s after input deactivation.

Terminal 20 (RD Access). Free wheel released

Note! Short circuit connection 20 and 21 with a jumper if no free wheel is installed.

Terminal 24. Safety loop output

Terminal 29. Safety loop input

The safety loop is supervised with a 1k resistor as reference value.

The door is stopped. The door starts again 1 s after the input is deactivated.



Terminal 31 (RD Access). Free wheel command

Terminal 33 (RD Access). Fire alarm

Note! Short circuit connection 33 and 34 with a jumper if no fire alarm is installed.

Terminal 35 (RD). El-mech. lock closed indication

Input is activated when the electromechanical lock is in locked position.

Terminal 35 (RD Access). Free wheel closed

Input is activated when the electromechanical lock is in locked position. **Note!** Short circuit connection 35 and 36 with a jumper if no electromechanical lock is installed.

Terminal 37 (RD). El-mech. lock open indication

Input is activated when the electromechanical lock is in open position. **Note!** Short circuit connection 37 and 38 with a jumper if no electromechanical lock is installed.

Terminal 37 (RD Access). Free wheel open

Input is activated when the electromechanical lock is in open position.

Digital outputs IOA 1-board

Terminal 39. Electromechanical Lock Power

Output +24 V when the electromechanical lock motor travels to closed position and 0 V when the electromechanical lock motor travels to open position.

Terminal 40. Electromechanical Lock Power

Output 0 V when the electromechanical lock motor travels to closed position and +24 V when the electromechanical lock motor travels to open position.

Terminal 46. PDR test

Function test of the PDR (if installed).

Terminal 50 (RD). Error signal 1

Terminal 51-52. Door status

Potential free contact. Output is activated when the door is rotating or is standing in locked position. (To be chosen in configuration option flag 21)

7.6 IOA 2-board

| | 5 | Conn | Term | | Description RD | Description RD Access |
|---|------------------|------|----------|---------|---------------------------|-----------------------|
| | 4 1, 3 | J12 | 1 | + | | |
| | 2 | | 2 | IN | | |
| | | | 3 | IN | | |
| | 13 (| | 4 | IN | | |
| | ∝ີ | | 5 | - | | |
| | റ | J13 | 6 | + | High speed impulse inner | |
| | 1 1 1 2 | | 7 | IN | | |
| | = | | 8 | - | | |
| | 3 12 | J14 | 9 | + | High speed impulse outer | |
| ÷ | 4 | | 10 | IN | - | |
| | 15 1 | 115 | 11 | - IN | Low speed impulse | |
| | 16 1 | J15 | 12 | 11N | Low speed impulse | |
| | 317 | | 13 | IN | Locked door command | |
| | 918 | | 14 | 111 | | |
| H | 0 % | | 16 | IN | Error clear | |
| | 212 J 16 | | 10 | | | |
| | 24 | | 18 | IN | Auto command | Security 3 inner |
| Ц | 25 | | 19 | | | |
| | 7 26 | J16 | 20 | IN | Key impulse | Security 3 outer |
| | 9 27 J 1 | | 21 | | | |
| | 29 2 | J17 | 24 | OUT | Emergency stop out | External jumper |
| | 30 | | 25 | IN | | |
| F | | | 26 | OUT | Emergency stop 2 loop out | |
| | | | 27 | IN | Emergency stop 2 loop in | |
| | | | 28 | OUT | Emergency stop1 loop out | |
| - | 5 | | 29 | IN | Emergency stop1 loop in | |
| | 8 32 3 8 | 110 | 30 | IN | | TT: 1 |
| | J-1 | J18 | 31 | IIN | Rotation lock command | High security command |
| | 34 | | 32 | IN | Brook out armod | |
| | 35 | | 33 | 111 | break-out armed | |
| H | 0 23 | I19 | 35 | IN | Break-out lower pos | |
| | 38 3 J 1(| 017 | 36 | | | |
| | 39 | | 37 | IN | Break-out top pos. | |
| | 40 | | 38 | ļ | | |
| | 4 | | 39 | OUT | Break-out motor | |
| | 3 42 | | 40 | OUT | 1 | |
| | J 20 | J20 | 41 | OUT | Break-out magnet | |
| | 45 4 | | 42 | IN | | |
| | 46 | | 43 | OUT | Rotation lock | Security level outer |
| | 47 21 | | 44 | IN | | |
| | 48 1 | | 45 | | Break-out motor relay | |
| | 49 | 10.1 | 46 | OUT | | |
| | 1 50 | J21 | 47 | UUT | Not used | |
| | 1 2 5 2 | 122 | 48 | | Error signal 2 | |
| ŀ | <u>0</u> | JZZ | 49 50 | IN | Enor signar 2 | |
| | 9 | | 51 | 111 | General alert | |
| | ∠ ∀ | | 52 | | | |
| | - | | 52 | | | |

Digital inputs IOA 2-board

Terminal 7. High Speed Start Inner Activation PIR or DSR, the door rotate 270°.

Terminal 10. High Speed Start Outer Activation PIR or DSR, the door rotate 270°.

Terminal 12. Low Speed Start Inner

If the door is rotating at a higher speed when input is activated, the speed is immediately reduced to "Low speed" for the rest of the rotation cycle or minimum 270° if start is reactivated.

Terminal 14. Lock door command.

The door rotate to closed position (home position). Electromechanical, if fitted, will be activated and lock.

Terminal 16. Error Clear

Error reset push button input. Same function as "C"-button on the PCD.

Terminal 18. Auto command.

Outside and Inside impulse will activate the door. Unlock electromechanical (if fitted).

Terminal 20. Key impels.

Unlock electromechanical lock if fitted and the door will rotate 360° and lock again.

Terminal 24. Emergency stop loop output

Terminal 29. Emergency stop loop input (error code 20)

Stop button 1 located inside is mandatory and is equipped with a build-in 1k resistor.

The emergency stop button shall have a double normally closed contact.

Connector J17 connection 26, 27 and connector E-stop connection 3, 4 - Jumper or stop button 2.

The door is stopped with active brakes when the input is activated. The door starts again when the input is deactivated and the error condition is manually reset (press "C" on the PCD)



Terminal 31. Roto lock command. Input for Activation of Rotolock

Terminal 33. Break-out kit Micro switch indication that brake-out kit is armed.

Terminal 35. Break-out kit Micro switch indication lower position

Terminal 37. Break-out kit Micro switch indication upper position

Terminal 39. Break-out kit Motor

Terminal 40. Break-out kit Motor

Digital outputs IOA 2-board

Terminal 42. Brake-out kit Magnet

Terminal 43. Brake-out kit Magnet

Terminal 44. Rotation brake Rotation brake magnet. Activated by configuration option 35 Rotolock in parked position and input 31 Rotolock command.

Terminal 46. Brake-out kit Motor relay

Terminal 50.

Error signal 2

Terminal 51-52. General Alert

Potential free contact.

Output is activated instantly for all error codes and with a 10 second delay for all status codes.

7.7 IOB - board (RD Access only)

| 5 | Conn | Term | | Description |
|-------------|------|------|---------|--------------------------|
| | J2 | 1 | IN | Card reader inner |
| 2 4 | | 2 | - | |
| 9 P | | 3 | IN | Card reader outer |
| ~ | | 4 | - | |
| 8 | | 5 | IN | Push button inner |
| 6 0 | | 6 | - | D 11 |
| - - | | 7 | IN | Push button outer |
| 12 1 | | 8 | - IN | Que de l'incom |
| 13 | | 9 | IIN | Security 1 inner |
| 4 | 12 | 10 | - IN | Security 1 outer |
| 3 15 J 3 | 12 | 11 | 111 | Security 1 outer |
| 1710 | | 12 | IN | Security 2 inner |
| 18 | | 13 | - | Security 2 miler |
| 19 | | 15 | IN | Security 2 outer |
| 20 | | 16 | - | |
| | | 17 | IN | Hang sensor |
| | | 18 | - | |
| | | 19 | IN | Master access |
| 21 | | 20 | - | |
| 3 22 | J4 | 21 | RE1 | Card reader detect inner |
| 24 2 | | 22 | | |
| 25 | | 23 | RE2 | Card reader detect outer |
| 126 J. | | 24 | | |
| 8 27 | | 25 | RE3 | Passage detected inner |
| 2 2 | | 26 | DE4 | |
| 30 2 | | 27 | RE4 | Passage detected outer |
| 31 | | 28 | DE5 | Cross light inner |
| 32 | | 29 | KEJ | Green light limer |
| 4 33 | 15 | 31 | RE6 | Red light inner |
| 35 3 | 35 | 32 | ILL0 | |
| 36 (J 5 | | 33 | RE7 | Green light outer |
| 37 | | 34 | | |
| 938 | | 35 | RE8 | Red light outer |
| 60 3 | | 36 | 1 | - |
| | | 37 | RE9 | Vocal message start |
| | | 38 | 1 | |
| | | 39 | Jumper | Access alert |
| m - | | 40 | | |
| | | | | |

8

Program Control Device PCD, settings, operation

NOTE!

During all changes in settings the revolving door must be allowed to rotate 360° to enable the changes to be completed.

| Key | Function |
|-----|---|
| 0-9 | Numeric inputs |
| # | Confirm access code input |
| È | Setpoint selection upwards |
| Í | Setpoint selection downwards |
| + | Setpoint value change upwards |
| - | Setpoint value change downwards |
| F | Function selection |
| S | Setpoint confirmation and storage |
| С | Error reset Clear display Leave menu |
| | Lock door command to be connected to IOA 2 connection 14, 15 |



The PCD display blanks 10 or 30 seconds after the last

key stroke but still remains in the current function menu (see "Configuration options RD" on page 55).

Information prompts on PCD display

| Prompt | Description |
|--------|---|
| P1 | Locked door command ON |
| P2 | Service request To be shown after 300.000 revolutions (factory setting) |
| P3 | Real time operation ON |

PCD Function menu

The following functions can be controlled from the PCD:

- Change operating mode F2
- **F3** Adjust setpoints
- F4 Change access code
- F5 System configuration
- **F6 Diagnostic functions**
- F7 Real time clock functions
- **F8** Optional functions
- F9 System functions



8.1 Login/logout on PCD

To be able to make changes in the system it is necessary to login.

Login on PCD

- 1. Type # to clear the display.
- 2. Type the access code (4 digits). The display shows ----.
- 3. Type # to confirm the input. If the access code is correct the display shows LI (Log In) and the present access level.

If four unauthorized attempts to access the PCD are made in a row it takes five minutes before a new attempt can be made.

Logout on PCD

- 1. Type # to clear the display.
- 2. Type the access code (4 digits). The display shows ----.
- 3. Type # to confirm the input. If the access code is correct the display shows L0 (Log Out) and the present access level.

Automatic logout occurs ten minutes after the last key stroke. The automatic logout can be inhibited (see "Other PCD commands" on page 65)

8.2 Change operation mode RD

Type *F2*. The display shows F2 Use \uparrow or \downarrow to change operating mode. Confirm the change by typing *S*.



| Number | Operation mode | Function |
|-----------------|---|---|
| 01 | Lock door | The door rotates to closed position. If an electrome- chanical lock is fitted, the lock is activated. |
| 02 | Automatic operation, start from open posi- tion | The door is parked in open position when there is no traffic. As soon as the outside or inside activation units detect approaching traffic, the door starts rotat- ing. |
| 06 | Continuous rotation | The door rotates at low speed. As soon as the outside or inside activation units detect approaching traffic, the door accelerates to normal speed. The door returns to low speed when there is no traffic. |
| 07 ^a | Manual operation | The door rotates forward as long as the + key is depressed and reverse as long as the – key is depressed. |

a. During manual operation safety devices 10, 21, 22, 25, 26 are disconnected.

8.3 Change operation mode RD Access

Type *F2*. The display shows F2 Use \uparrow or \downarrow to change operating mode. Confirm the change by typing *S*.



RD 3-wing

| Number | Operation mode | Function |
|-----------------|-----------------------------------|---|
| 01 | Lock door | The door rotates to closed position. If an electrome- chanical lock is fitted, the lock is activated. |
| 02 | | |
| 03 | | |
| 04 | Access control Entry Free Exit | |
| 05 | No Entry Free Exit | |
| 06 | Free Entry Free Exit | The door is parked in open position when there is no traffic. As soon as the outside or inside activation units detect approaching traffic, the door starts rotating. |
| 07 ^a | Manual operation | The door rotates forward as long as the + key is depressed and reverse as long as the – key is depressed. |

a. During manual operation safety devices 10, 21, 22, 25, 26 are disconnected.

RD 4-wing

| Number | Operation mode | Function |
|-----------------|---|---|
| 01 | Lock door | The door rotates to closed position. If an electrome- chanical lock is fitted, the lock is activated. |
| 02 | Access control Entry Access control Exit | |
| 03 | No Entry Access control Exit | |
| 04 | Access control Entry Free Exit | |
| 05 | No Entry Free Exit | |
| 06 | Free Entry Free Exit | The door is parked in open position when there is no traffic. As soon as the outside or inside activation units detect approaching traffic, the door starts rotating. |
| 07 ^a | Manual operation | The door rotates forward as long as the + key is depressed and reverse as long as the – key is depressed. |

a. During manual operation safety devices 10, 21, 22, 25, 26 are disconnected.

8.4 Adjustment RD

Type *F3*. The display shows S1.

Use \uparrow or \downarrow to select setpoint number,

Use + or - to change setpoint value.

Type S to confirm the new setting.

The display shows SSSS and then blanks.



Press C to leave the setpoint menu without changing any settings.

EAA158

| Setpoint | Description | Setpoint value | |
|------------|-----------------------------------|------------------|--|
| S 1 | High speed setpoint | 1-6 rpm | |
| S2 | Low (handicap) speed setpoint | 0.2-2.5 rpm | |
| S 3 | Creep speed setpoint | Fixed at 0,5 rpm | |
| S4 | Continuous speed setpoint | 1.0-2.5 rpm | |
| S5 | Manual speed setpoint | 0.2-2.0 rpm | |
| S9 | Door force parameter ^a | 01-09 | |

a. Used to set the balance between force/acceleration and detection of blocked door (error code 30) Default 06.

Note! For safe speed setting see STI 04-014 (Sales and Technical Information)

8.5 Adjustment RD Access

Type *F3*. The display shows S1.

Use \uparrow or \downarrow to select setpoint number,

Use + or - to change setpoint value.

Type *S* to confirm the new setting.

changing any settings.

The display shows SSSS and then blanks.

Press C to leave the setpoint menu without

1/↓ 5 1 func +/- 3 0 data

EAA158

| Setpoint | Description | Setpoint value |
|----------|-----------------------------------|------------------|
| S1 | High speed setpoint | 1-6 rpm |
| S2 | Low (handicap) speed setpoint | 0.2-2.5 rpm |
| S3 | Creep speed setpoint | Fixed at 0.5 rpm |
| S4 | Continuous speed setpoint | 1.0-2.5 rpm |
| S5 | Manual speed setpoint | 0.2-2.0 rpm |
| S9 | Door force parameter ^a | 01-09 |
| 10 | Push button inner enable time | 00-20 sec |
| 11 | Push button outer enable time | 00-20 sec |
| 12 | Start delay inner | 00-10 sec |
| 13 | Start delay outer | 00-10 sec |
| 14 | Hold before reverse time | 00-10 sec |

a. Used to set the balance between force/acceleration and detection of blocked door (error code 30) Default 06.

Note! For safe speed setting see STI 04-014 (Sales and Technical Information)

8.6 Change access code

To enable door operation from the PCD it is necessary to have an access code. The access code also determines which service level that is obtained.

At delivery the access code to level 1 is 1234. To change the access code do as follows:

Login with the existing access code.

Type F41. The display shows F4/L1.

Type the new access code.

Type S to confirm.

Type the new access code a second time.

Type *S* to confirm.

If the new access code has been accepted, the display shows CCCC and then blanks.

If the new access code not has been accepted, the display shows EEEE and then blanks.

8.7 Set home position

Make sure that the encoder is firmly fixed. Home position is the same as locked position.

Move the door to home position/locked position by hand or by manual operation.

Type *F514*. The display shows 1401.



EAA159

Type S to confirm. The display shows SSSS and then blanks.

8.8 Adjust safety zone

Only for doors with optional PDR

The safety zone has a fixed segment of 10° and an adjustable segment of 30° . The sensors are active until the door leaf has passed the drum edge.



Type F523. The display shows 23 and the present adjustable safety zone.

Press + or - to select new safety zone within the adjustable 30° segment.

Type *S* to confirm the new setting. The display shows SSSS and then blanks.

8.9 Configuration options RD

Type F53. The display shows an option number and its setting, e g: 03 01.

Use \uparrow or \downarrow to select option number.

Press + or - to select setting 00 or 01, see "Option settings" below.

Type *S* to confirm the new setting.



EAA166

| Option no. | Description | Default setting | Remark |
|------------|---|-----------------|---|
| 02 | Summertime | 01 | 00=No; 01=Yes |
| 04 | Lights OFF in locked position | 01 | 00=No; 01=Yes |
| 06 | Short PCD edit timeout | 01 | 00=30 sec.; 01=10 sec. |
| 17 | Electromechanical lock installed | 00 | 00=No; 01=Yes |
| 18 | Display default PCD message "ON" | 01 | 00=No; 01=Yes |
| 20 | Event log printer on MDT channel | 00 | 00=No; 01=Yes |
| 21 | 21 Door status output active door running | | 00=on when door is locked 01=on when door rotate |
| 22 | Service prompt always visible | 01 | 00=No; 01=Yes |
| 30 | 3-wing option | 00 | 00=No; 01=Yes |
| 31 | PDR installed | 00 | 00=No; 01=Yes |
| 32 | PCD installed | 00 | 00=No; 01=Yes |
| 33 | Safety zone 360° | 00 | 00=No; 01=Yes |
| 34 | Rotolock installed | 00 | 00=No; 01=Yes |
| 35 | Active rotolock in parked position | 00 | 00=No; 01=Yes |
| 36 | Break-out kit installed | 00 | 00=No; 01=Yes |
| 37 | Emergency operation option | 00 | 00=No; 01=Yes |
| 38 | Second motor installed | 00 | 00=No; 01=Yes |
| 39 | Door in escape route | 00 | 00=No; 01=Yes |

Configuration options RD Access 8.10

Type *F53*. The display shows an option number and its setting, e g: 03 01.

Use \uparrow or \downarrow to select option number.

Press + or - to select setting 00 or 01, see "Option settings" below.

Type *S* to confirm the new setting.



EAA166

| | | | EAA166 |
|------------|--|-----------------|---|
| Option no. | Description | Default setting | Remark |
| 01 | Battery installed | 01 | 00=No; 01=Yes |
| 02 | Summertime | 01 | 00=No; 01=Yes |
| 04 | Lights OFF in locked position | 01 | 00=No; 01=Yes |
| 06 | Short PCD edit timeout | 01 | 00=30 sec.; 01=10 sec. |
| 18 | Display default PCD message "ON" | 01 | 00=No; 01=Yes |
| 20 | Event log printer on MDT channel | 00 | 00=No; 01=Yes |
| 21 | Door status output active door running | | 00=on when door is locked 01=on when door rotate |
| 22 | Service prompt always visible | 01 | 00=No; 01=Yes |
| 30 | 3-wing option | 00 | 00=No; 01=Yes |
| 31 | PDR installed | 00 | 00=No; 01=Yes |
| 32 | PCD installed | 00 | 00=No; 01=Yes |
| 33 | Safety zone 360° | 00 | 00=No; 01=Yes |
| 36 | Break-out kit installed | 00 | 00=No; 01=Yes |
| 37 | Emergency operation option | 00 | 00=No; 01=Yes |
| 38 | Second motor installed | 00 | 00=No; 01=Yes |
| 39 | Door in escape route | 00 | 00=No; 01=Yes |
| 40 | Touchless ESPE installed | 00 | 00=No; 01=Yes |
| 41 | Freewheel in OFF condition | 00 | 00=No; 01=Yes |
| 42 | Queue function enabled | 01 | 00=No; 01=Yes |
| 43 | Traffic light function | 01 | 00=No; 01=Yes |
| 44 | BOK release in emergency position | 00 | 00=No; 01=Yes |
| 45 | Antipiggyback In installed | 00 | 00=No; 01=Yes |
| 46 | Antipiggyback Out installed | 00 | 00=No; 01=Yes |

8.11 Check of Input and output status RD

Type *F611* for IOA 1 or *F612* for IOA 2. The display shows a input channel number and the present status of the channel.

Use \uparrow or \downarrow to display the desired input channel \uparrow/\downarrow number and its present status.

| Display | Status |
|---------|--------------------|
| 00 | Low input, steady |
| 01 | High input, steady |



Press *C* to leave the menu.

| Channel number | IOA 1 | IOA 2 |
|-------------------|------------------------|--------------------------|
| 02 | Encoder 0-pulse | Not used |
| 03 | Encoder A-pulse | Not used |
| 04 | Encoder B-pulse | Not used |
| 07 | Vertical sensor PDR1 | High speed impulse inner |
| 10 | Vertical sensor PDR2 | High speed impulse outer |
| 12 | Not used | Low speed impulse |
| 14 | Not used | Locked door command |
| 16 | Slow drive input (CFD) | Error clear "C" |
| 18 | Stop drive input (CFD) | Auto command |
| 20 | Not used | Key impulse |
| 29 | Safety input | Emergency stop 1 |
| 31 | Not used | Rotation lock command |
| 33 | Not used | Break-out armed |
| 35 | El-mech. lock locked | Break-out lower pos. |
| 37 | El-mech. lock open | Break-out top pos. |
| 39 | El-mech. lock motor | Break-out motor |
| 40 | El-mech. lock motor | Break-out motor |
| 42 | Not used | Break-out magnet |
| 44 | Not used | Rotation lock |
| 46 | PDR test | Break-out motor relay |
| 50 | Error signal 1 | Error signal 2 |
| 51 | Door status | General alert |

Check of Input and output status RD Access 8.12

Type *F611* for IOA 1, *F612* for IOA 2 or *F613* for IOB. The display shows a input channel number and the present status of the channel.

Use \uparrow or \downarrow to display the desired input channel number and its present status.

| Display | Status | |
|-----------------------------------|-------------------|--|
| 00 | Low input, steady | |
| 01 High input, steady | | |
| Press <i>C</i> to leave the menu. | | |



EAA167

| Channel number | IOA 1 | IOA 2 | ЮВ |
|-------------------|---------------------------------|--------------------------|------------------------|
| 01 | Not used | Not used | Card reader in |
| 02 | Encoder 0-pulse | Not used | Card reader out |
| 03 | Encoder A-pulse | Not used | Not used |
| 04 | Encoder B-pulse | Mechanical lock | Not used |
| 05 | Not used | Not used | Push button in |
| 07 | Vertical sensor PDR1 | High speed impulse inner | Push button out |
| 09 | Not used | Not used | Security 1 in |
| 10 | Vertical sensor PDR2 | High speed impulse outer | Not used |
| 11 | Not used | Not used | Security 1 out |
| 12 | Not used | Low speed impulse | Not used |
| 13 | Not used | Not used | Security 2 in |
| 14 | Not used | Locked door command | Not used |
| 15 | Not used | Not used | Security 2 out |
| 16 | Slow drive input | Error clear "C" | Not used |
| 17 | Not used | Not used | Hang sensor |
| 18 | Stop drive input | Not used | Not used |
| 19 | Not used | Not used | Master access |
| 20 | Free wheel released | Not used | Not used |
| 21 | Not used | Not used | Card reader detect in |
| 23 | Not used | Not used | Card reader detect out |
| 25 | Not used | Not used | Passage detect in |
| 27 | Not used | Not used | Passage detect out |
| 29 | Safety input (S 10) | Emergency stop (E 20) | Green light in |
| 31 | Free wheel command | Not used | Red light in |
| 33 | Fire alert input | Break-out armed | Green light out |
| 35 | Freewheel motor closed position | Break-out lower pos. | Red light out |
| 37 | Freewheel motor open position | Break-out top pos. | Vocal message start |
| 39 | Freewheel motor | Break-out motor | Access alert |
| 40 | Freewheel motor | Break-out motor | Not used |
| 42 | Not used | Break-out magnet | - |
| 44 | Not used | Not used | - |
| 46 | PDR test | Break-out motor relay | - |
| 50 | Error signal 1 | Error signal 2 | - |
| 51 | Door status | General alert | - |

8.13 Real time clock

The CDC system has a real time clock build in. The clock is used for log records and for real time settings when the door is running.

The real time clock is set during installation. After three, four months the clock is calibrated.

Normally it is only necessary to calibrate the clock once.

8.13.1 Read real time clock

Type *F71*. The display shows 11 and present parameter value relating to year.

Use \uparrow or \downarrow to select parameter number and display the parameter value.

Press *C* to leave the menu.



Year
 Month
 Date
 Hour
 Minute
 Second

EAA168

8.13.2 Set real time clock

Before setting date and time, set "Summertime" to "Yes" or "No" in "Configuration options RD" on page 55.

Type **F72**. The display shows 21 and present parameter value relating to year.

Use \uparrow or \downarrow to select parameter number and display the parameter value.

Use the number keys *1–9* to change the parameter value.

Type *S* to confirm each new setting.

Press *C* to leave the menu.

8.13.3 Calibrate real time clock

Type *F73*. The display shows 31 and present parameter value relating to year.

Use \uparrow or \downarrow to select parameter number and display the parameter value.

Use the number keys *1–9* to change the parameter value.

Type *S* to confirm each new setting.

Press *C* to leave the menu.



| 1004466-EI-2. | U | I |
|---------------|---|---|
|---------------|---|---|

8.14 Log functions

The event log records and time stamps 600 events in a circular buffer in the CDC system.

As an option a printer can be connected to the COM port to print out the system events.

Refer to code list on opposite page for flag numbers.

8.14.1 Set event log flags

Type *F541*.

The display shows the flag number and the present flag status, 00=OFF and 01=ON.

Use \uparrow or \downarrow to select flag number and display its present status.

Use + or - to change the flag status.

When all event log flags have been set, type S to confirm the new setting. The display shows SS41 and then blanks.



EAA173

EAA173

8.14.2 Set event print flags

Events to be printed or shown on screen (not saved in event log).

Type *F542*.

The display shows the print flag number and the present print flag status, 00=OFF and 01=ON.



Use \uparrow or \downarrow to display the select print flag number and display its present status.

Use + or - to change the print flag status.

When all event print flags have been set, type S to confirm the new setting. The display shows SS42 and then blanks.

| Code | Description | Туре | Action |
|------|------------------------|----------------------|---|
| In | Door initiation run | Status | Looking for 0 pulse. If the door do not operate with this code, |
| | | | check that the door is not set to manual mode 07 |
| On | Normal condition | Status | If the door do not operate with this code, check that the door is |
| | | | not set to manual mode 07 |
| 05 | Power fail test | Error (24 hour test) | Reset. If error code appears again check cable MPU to DPC |
| 06 | A /D 1 | F arra a | next replace DPC |
| 06 | A/B pulse | Error | Missing A or B pulse from encoder. Check cabling and slip |
| 07 | Zero nulse | Frror | Missing 0 pulse from encoder. Check cabling and slip ring |
| 10 | Safety stop | Status | Check safety loop |
| 11 | El-mech, lock | Error | Check micro switch, for lock in open position. |
| 17 | Door manually | Event | Log only |
| | pushed | | |
| 18 | Rotation direction | Error | Wrong cabling on A/B pulse from encoder or wrong motor |
| | error | | cabling. |
| 19 | Over speed | Error | Door pushed to speed over 5 rpm. |
| 20 | Emergency stop | Error | Turn emergency stop button, restart by press "C". If cables for |
| | | | stop button are damage and in contact with ground, error 20 |
| 21 | Vertical concern 1DDD | States | will also appear. |
| 21 | (inner) | Status | Adjust sensor above entrance. (see vertical PDR on page 120) |
| 22 | Vertical sensor 2 | Status | Adjust sensor above entrance (see "Vertical PDR" on page |
| | PDR (outer) | Statub | 120). |
| 25 | Slow drive input | Status | Eyetech Information. |
| 26 | Stop drive input | Status | Eyetech Information. |
| 29 | General alert output | Status | Output on IOA/2 connection 51-52. Log only. |
| 30 | Blocked door | Error | Push the door by hand to check so there is no mechanical rea- |
| | | | sons obstacles in the door, gearbox, brake, belt or lock prob- |
| | | | lem. If the door can be moved by hand, check that motor |
| | | | cables are connected. Check connection E-STOP correct |
| | | | emergency button = jumper between $1-2$ or $3-4$. |
| 31 | Fire alarm input | Status | If not used, jumper between 33-34. Must be potential free con- |
| | I | | tact from fire alarm system. |
| 32 | Power fail | Status | Lost of power supply. |
| 36 | Battery error | Error | Battery not connected or not charged. Charge the battery for |
| | | | approx. 48 hour. |
| 39 | Security stop | Status | Security stop request |
| 41 | Freewheel | Error | Check micro switch |
| 42 | Freewheel Command | Event | Log only |
| 43 | Freewheel Released | Status | Deactivate Freewheel command I/O-A 1 J18 connection 31- |
| ΛΛ | Security start in from | Event | J2 Log only |
| 44 | MDT | Lvent | |
| 45 | Security start out | Event | Log only |
| _ | from MDT | | |
| 46 | PSE calibrate | Event | |
| 47 | PSE system in ok | Status | |
| 48 | PSE system out ok | Status | |
| 49 | PSE high security | Event | |
| 4A | Security 3 in | Event | |

| 8.14.3 | 3 (| Cod | e li | ist |
|--------|-----|-----|------|-----|
| | | | | |

| Code | Description | Туре | Action |
|------|---------------------------------|---------------------|--|
| 4B | Security 3 out | | |
| 56 | Motor deactivation | Error (20 min test) | Reset, if error code appears again after 20 min., replace DPC board. (Code 56 can appear if door is pushed during it's test.). |
| 57 | Brake distance | Error | Check brakes function |
| 58 | Safety loop input | Error | Reset, if error code appears again replace IOA/1. |
| 59 | Emergency stop loop | Error | Reset, if error code appears again replace IOA/2. |
| 69 | 20 minutes test | Event | Log only. |
| 71 | MPU prom | Error | Reset. If error code appear again replace MPU. |
| 72 | MPU internal RAM | Error | Reset. If error code appear again replace MPU. |
| 73 | MPU external RAM | Error | Reset. If error code appear again replace MPU. |
| 74 | MPU watchdog | Error (20 min test) | Reset. If error code appear again replace MPU. |
| 75 | Watchdog supervi- sor Init | Error | Reset. If error code appear again replace MPU. |
| 76 | Watchdog supervi- sor Timing | Error | Reset. If error code appear again replace MPU. |
| 77 | Reset F911 or reset | Event | Log only |
| | button | | |
| 78 | Flash Loading | Event | Log only |
| 79 | 24 hour test | Event | Log only |
| 81 | Lock door | Mode | Log only |
| 82 | Auto open | Mode | Log only |
| 86 | Continuous | Mode | Log only |
| 87 | Manual | Mode | Log only |
| 89 | Real Time | Event | Log only |
| 91 | High speed start inner | Impulse | Log only |
| 92 | High speed start outer | Impulse | Log only |
| 93 | Low speed start | Impulse | Log only |
| 95 | Key | Impulse | Log only |
| 97 | Evacuate | Impulse | Log only |
| 98 | Lock door command | Mode | Log only |
| 99 | Service request | Even | Log only |
| 9A | Motor overheated | Error | Check the motors. |
| 9D | Internal EEPROM | Error | Reset. If error code appears again change MPU. |
| 9F | Motor signals | Error (20 min test) | Reset. If error code appear again change MPU. |
| A1 | Card reader in | Event | Log only |
| A2 | Card reader out | Event | Log only |
| A3 | Push button in | Event | Log only |
| A4 | Push button out | Event | Log only |
| A5 | Security 1 in | Event | Log only |
| A6 | Security 1 out | Event | Log only |
| A7 | Security 2 in | Event | Log only |
| A8 | Security 2 out | Event | Log only |
| A9 | Hang sensor | Event | Log only |
| AA | Master access | Event | Log only |
| AB | Card reader detect in | Event | Log only |
| AC | Card reader detect out | Event | Log only |
| AD | Passage detect in | Event | Log only |
| AE | Passage detect out | Event | Log only |

| Code | Description | Туре | Action |
|------------|---------------------|---------------------|--|
| C2 | BOK magnet no cur- | Status | Check break-out kit |
| | rent | | |
| C3 | BOK not armed | | Check the lower microswitch on the break-out kit. |
| D0 | Watch dog AVR | Error (20 min test) | Reset. If error code appear again change MPU. |
| D1 | Battery load test | Error (20 min test) | If it's appear during installation charge the battery. If battery is |
| | | | 2-3 years old Change battery. |
| D2 | Motor current meas- | Error | Difference between M1 and motor 2 is to big, Check the |
| | ure | | motors (carbon) |
| D3 | Motor regulator | Error | |
| D4 | PDR 1 vertical sen- | Error | Check cabling and PDR |
| | sor test signal | | |
| D5 | PDR 2 vertical sen- | Error | Check cabling and PDR |
| | sor test signal | | |
| D6 | Emergency stop but- | Error | Appear only in log, if test of stop button command F938 is |
| | ton TEST | | done and the test fail. |
| D7 | M16C ROM | Error | Cut power and start again. |
| | | | If error code appear again replace MPU. |
| D8 | M16C RAM | Error | Cut power and start again. |
| | | _ | If error code appear again replace MPU. |
| D9 | Link error timeout | Error | Cut power and start again. |
| | | | If error code appear again replace MPU. |
| DA | SPI overflow | Error | Cut power and start again. |
| DD | an a | | If error code appear again replace MPU. |
| DB | CRC | Error | Cut power and start again. |
| DC | CDI 1 | | If error code appear again replace MPU. |
| DC | SPI msg. too long | Error | Cut power and start again. |
| DD | | . | If error code appear again replace MPU. |
| DD | System SPI | Error | Cut power and start again. |
| DE | 0 | . | If error code appear again replace MPU. |
| DE | Over current | Error | Cut power and start again. |
| DE | 0 7 | Г | If error code appear again replace MPU. |
| DF | Queue overflow | Error | Cut power and start again. |
| EO | DCIDT | F actor | Il error code appear again replace MPU. |
| EU | BC 121 | Error | Speed slows down until brake resistors have normal temp. |
| EI | BC 121 | Error | Change DPC board. |
| E2 | BOK | Error | Reset 2 times. If error code appear again check the top and the |
| F 2 | DOK | <u></u> | middle microswitch on the break out kit. |
| E3 | BOK magnet no cur- | Status | Check break-out kit |
| F 4 | | Charles - | |
| E4 | BOK not armed | Status | Cneck break-out kit |
| E5 | Rotolock switch | Status | Rotolock switch activated. |

8.14.4 Print out of event log

To avoid problems, use a printer recommended by Besam. The printer is then correctly setup and with a suitable cable.

Set configuration option no. 20 to 01=Yes (see "Configuration options RD" on page 55)

Connect the printer to the COM port connector at the side of the CDC-unit. (see "Main processing unit, MPU" on page 41)

Print out of the entire log (up to 600 events)

Type **F545**

Stop print out

Type **F546**

Print out of one selected event code

Type *F543* The display shows the event code. Use \uparrow or \downarrow to select the event code to print. Type *S* to confirm.

Type F544 to print out the selected event code.



8.14.5 Print out of selected events

To be able to identify problems that happens just now and then it is possible to leave the printer connected to the system and print out a selection of events during a longer period of time. The selected events will then be printed when they are logged.

Select events to be printed by setting event print flags (see "Set event print flags" on page 60)

8.15 Other PCD commands

- F543 Select event code to print
- F544 Print selected events
- F545 Print entire event log
- F546 Abort event log printing
- F547 Select event log display format
- F551 Display MPU program version
- F552 Switch MDT channel ON
- F553 Switch MDT channel OFF
- F556 Real time operation mode ON
- F557 Real time operation mode OFF
- F561 Automatic logout inhibit
- F562 Clear revolution counter
- F563 Clear event log
- F564 Clear service prompt and start new period
- F565 Calibration ON
- F566 Calibration OFF
- F911 System reset
- F921 Restore all access codes
- F922 Restore speed setpoints
- F923 Restore config option flags
- F924 Restore safety. Start position offset
- F925 Restore event log flag
- F931 Disconnect battery

Main Diagnostic Terminal MDT, operation

To adjust settings and perform maintenance on the CDC system a VT100 Terminal or a PC can be connected and used as a Main Diagnostic Terminal instead of the PCD.

9.1 Connection

The MDT is connected directly at the COM port at the side of the CDC-unit. To enable usage of a PC as MDT

- 1. Start Hyperterminal under Accessories
- 2. Make the following settings
 - 8 bits data
 - No parity
 - One stop bit
 - 9600 baud

Use a standard Null Modem cable (9 pin).



9.2 Software update

An update can only be performed on a CDC4 system already running an operational version of the CDC4 application software, in other words, MDT login must be possible, if this is not the case, skip to the section describing initial software load.

Normal door operation is not possible during the update procedure, so it should be positioned in its escape position or closed for access.

IMPORTANT!

The old version must reside in flash memory bank P1 or the update will fail. Start by checking where the program is installed, P1 or P0.

Login to the CDC via comport and check under the CDC Main Menu the information software release. The program change automatically from download to P0 next P1 next P0 etc.

To have a successful updating next time, install the latest version two times so it ends in P1.

This example is OK

| | CDC Main Menu | |
|------------------|--------------------------------|----|
| Door Type | : RD3/4 - CDC42 | |
| Software Release | : Ver 4.01 B 13 P1 #FA8 | 3C |

In this cases the update will fail!

CDC Main Menu

| Door Type | : | RD3/4 - CDC42 |
|------------------|---|------------------------|
| Software Release | : | Ver 4.01 B 13 P0 #FA8C |



The download starts automatically

```
(A4CC)
Wait for CDC to be ready
3 2 1 0
Enter flash programming mode ******** OK
FL V1.05 Page 0
Changing baudrate to 19200 baud...OK
Erase...OK
Download in binary format...
Size of application is 207760 bytes
08-----
--100%
XXXXXX
OK
Writing checksum...(A4CC)
OK
Ver-
ify...OK
Config =
09
Reset...OK
Resetting...
DONE!
To start : If nobody is logged in press SPACE else reset
         the MPU and then press RETURN
```

To quit: Press Escape



The watchdog supervisor indicator LED (S) is shining if the update was successful. Download the update once more in the P1 memory bank.

9.2.2 Initial software load (Boot load)

EAA823

If there is no program loaded or if the update fails (the watchdog supervisor indicator LED did not lit up), the program has to be boot loaded.

- 1. Apply a programming contact to connector J11 (D).
- 2. Press the reset button (L).
- 3. Follow the procedures described in the previous chapter (update procedure) but with the MPUBOOT.EXE-file located in the Boot-library instead of the MPUFLASH.EXE-file.
- 4. Remove the programming contact.
- 5. Press the reset button (L).



9.4 Login

To enable login on the MDT the PCD must be logged out. Enter access code: **** OK The CDC Main Menu appears on the display. If the display show: !!!!! the PCD is logged in

9.5 Main menu

CDC Main Menu

Door Type : RD3/4 - CDC42 Software Release : Ver 1.01.21 P1 #D352 2007-05-27 M16C H/S Release : Ver 1.01.10 Press key to select function: 1: Door Operation 2: Configuration 3: Diagnostic Functions 4: Log Functions 5: Development Functions 6: Logout

Press the number key relating to the number in front of the desired submenu to select.

Press *ESC* to go to this menu from any sub-menu.
9.6 Door operation RD

| CDC | Door Operation Page |
|--|-------------------------------------|
| Error/Status Display: Operating Mode: Door Speed (RPM/10): | ON 2 sPCD In AUTO 30 |
| Revolution Counter: Date & Time: | 3697 Tuesday 2007-05-25 10:29:08 |
| Operating modes: 1: Lock Door 2: Auto = Start from open posit | ion |
| 6: Continuous Rotation7: Manual Operation8: Summer Position9: Automatic Service Doors | |
| Press function key: | C: Error Clear I: Key Impulse |
| | R: Real Time Operation ON/OFF |

To select operation mode, press the key relating to desired operation mode. Press *Enter* to confirm changes. Press *ESC* to return to main menu.

9.6.1 Other information on Door operation screen

sPCD

In OFF In Auto In Continuous

Service request

The door have been running for 300.000 revolutions. Type *F564* on the PCD to clear service prompt and reset the service period.

Real time

Real time operation is active Type *R* to toggle between real time operation ON/OFF.

9.7 Door operation RD Access

9.7.1 3-wing

| | CDC Door Operation Page |
|--|---|
| Error/Status Display: Operating Mode: Door Speed (RPM/10): | ON 2 3 0 |
| Revolution Counter: Date & Time: | 3697 Tuesday 2007-05-07 11:12:08 |
| Operating modes: 1: Lock Door | |
| 4: Security In - Free Out 5: Closed In - Free Out 6: Free In - Free Out 7: Manual Operation | |
| Press function key: | C: Error Clear |
| | O: Outer Access signal M: Master Access R: Real Time Operation ON/OFF |
| Press the n | umber key relating to the number in front of the d |

Press the number key relating to the number in front of the desired operation mode to select.

Press *Enter* to confirm changes. Press *ESC* to return to main menu.

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9.7.2 4-wing

| CDC I | Door Operation Page |
|--|--|
| Error/Status Display: Operating Mode: Door Speed (RPM/10): | ON 2 3 0 |
| Revolution Counter: Date & Time: | 3697 Tuesday 2007-05-07 11:12:08 |
| Operating modes: 1: Lock Door 2: Security In - Security Out 3: Closed In - Security Out 4: Security In - Free Out 5: Closed In - Free Out 6: Free In - Free Out 7: Manual Operation | |
| Press function key: | C: Error Clear I: Inner Access Signal O: Outer Access signal |

- M: Master Access
- R: Real Time Operation ON/OFF

To select operation mode, press the key relating to desired operation mode. Press *Enter* to confirm changes. Press *ESC* to return to main menu.

9.7.3 Other information on Door operation screen

Service request

The door have been running for 300.000 revolutions. Type *F564* on the PCD to clear service prompt and reset the service period.

Real time

Real time operation is active

Type R to toggle between real time operation ON/OFF.

9.8 Configuration menu

CDC Configuration Menu

Press key to select function:

- 1: Adjustments
- 2: Configuration Options
- 3: Real Time Clock
- 4: Real Time Operation
- 5: Change Access Codes (not used)

To select operation mode, press the key relating to desired operation mode. Press *ESC* or X to return to main menu. Real time operation (see "Real time operation" on page 92)

9.8.1 Adjustments RD

| CDC Adjustment Page | | |
|----------------------------|----------|----|
| High Speed | (RPM/10) | 60 |
| Low Speed | (RPM/10) | 25 |
| Creep Speed | (RPM/10) | 5 |
| Continuous Speed | (RPM/10) | 30 |
| Manual Speed | (RPM/10) | 20 |
| Safety Zone Offset | | 0 |
| Door Force Parameter (1-9) | | 5 |
| Door Diameter (dm) | | 36 |

Use Tab-key to select value to change. \blacksquare

Use number keys to enter new value.

Press *Enter* to confirm each change. 🖃

Type *X* to return to the previous menu or *ESC* to return to main menu.

| Setpoint | Setpoint value |
|----------------------|------------------|
| High speed | 1-6 rpm |
| Low (handicap) speed | 0.2-2.5 rpm |
| Creep speed | Fixed at 0.5 rpm |
| Continuous speed | 1.0-2.5 rpm |
| Manual speed | 0.2-2.0 rpm |
| Door force | 1-9 |

Door diameter

Type the door size (1.8-3.6).

9.8.2 Adjustments RD Access

| CDC Adjustment Page | | |
|---------------------------------|----------|-----|
| High Speed | (RPM/10) | 30 |
| Low Speed | (RPM/10) | 15 |
| Creep Speed | (RPM/10) | 5 |
| Continuous Speed | (RPM/10) | 10 |
| Manual Speed | (RPM/10) | 10 |
| Safety Zone Offset | | 10 |
| Door Force (1-9) | | 5 |
| Door Diameter (dm) | | 21 |
| Push Button In Enable Time (s) | | 2.0 |
| Push Button Out Enable Time (s) | | 20 |
| Start Delay In (s) | | 10 |
| Start Delay Out (s) | | 10 |
| Hold Before Reverse Time (s) | | 10 |

Use number keys to enter new value.

Press *Enter* to confirm each change. 🖃

| Setpoint | Setpoint value |
|-----------------------------|------------------|
| High speed | 1-6 rpm |
| Low (handicap) speed | 0.2-2.5 rpm |
| Creep speed | Fixed at 0.5 rpm |
| Continuous speed | 1.0-2.5 rpm |
| Manual speed | 0.2-2.0 rpm |
| Door force | 1-9 |
| Door diameter | 18-24 dm. |
| Push button in enable time | 00-20 sec |
| Push button out enable time | 00-20 sec |
| Start delay in | 00-10 sec |
| Start delay out | 00-10 sec |
| Hold before reverse time | 00-10 sec |

Configuration options RD 9.8.3

| CDC | Configuration Options Page 1 | |
|-----|--|---|
| 2: | Summertime | 1 |
| 4: | Lights Off In Locked Position | 1 |
| 17: | Electromechanical Lock Installed | 0 |
| 18: | Display Default PCD Message ON | 1 |
| 20: | Event Log Printer on MDT Channel | 0 |
| 21: | Door Status Output Active Door Running | 1 |
| 22: | Service Prompt Always Visible | 1 |
| CDC | Configuration Options Page 2 | |
| 30 | 3 Wing Option | 0 |
| 31 | PDR Installed | 0 |
| 32 | PCD Installed | 0 |
| 33 | Safety Zone 360° | 0 |
| 34 | Rotolock Installed | 0 |
| 35 | Active Rotolock in Parked Position | 0 |
| 36 | Break Out Kit Installed | 0 |
| 37 | Emergency Operation Option | 0 |
| 38 | Second Motor Installed | 0 |
| 39 | Door In Escape Route | 0 |
| Use | Tab-key to select value to change. | |
| Use | number keys 1 or 0 to enter new value. | |

Press *Enter* to confirm each change.

Type *N* to display next page.

Type P to display previous page.

Configuration options RD Access 9.8.4

| CDC | Configuration Options Page 1 | |
|-------|--|---|
| 1: | Battery Installed | 1 |
| 2: | Summertime | 0 |
| 4: | Lights Off In Locked Position | 1 |
| 6: | Short PCD Edit Timeout | 1 |
| 18: | Display Default PCD Message ON | 1 |
| 20: | Event Log Printer on MDT Channel | 0 |
| 21: | Door Status Output Active Door Running | 0 |
| 22: | Service Prompt Always Visible | 1 |
| CDC | Configuration Options Page 2 | |
| 30 | 3 Wing Option | 0 |
| 31 | PDR Installed | 0 |
| 32 | PCD Installed | 1 |
| 33 | Safety Zone 360° | 0 |
| 36 | Break Out Kit Installed | 0 |
| 37 | Emergency Operation Option | 0 |
| 38 | Second Motor Installed | 0 |
| 39 | Door In Escape Route | 0 |
| 40 | Touchless ESPE Installed | 0 |
| 41 | Freewheel in OFF Condition | 0 |
| 42 | Queue Function Enabled | 1 |
| 43 | Traffic Light Function | 1 |
| 44 | BOK Release in Emergency Position | 0 |
| CDC | Configuration Options Page 3 | |
| 45 | Anitpiggyback In installed | 0 |
| 46 | Anitpiggyback Out installed | 0 |
| Use 2 | Tab-key to select value to change. | |
| Use | number keys 1 or 0 to enter new value. | |
| Press | <i>Enter</i> to confirm each change. | |

Type N to display next page.

Type P to display previous page. Type X to return to the previous menu or ESC to return to main menu.

9.8.5 Set real time clock

CDC Real Time Clock Menu Press key to select function: Date & Time: Tuesday 2005-05-24 10:32:50 1: Set Date and Time 2: Calibrate Clock 3: Set Daily Test Time

Set date and time

CDC Set Real Time Clock Menu Date & Time: Saturday 2000-01-01 00:08:40 Enter New Date (yyyy mm dd): 20000501 New Date Entered = 2000-05-01 Enter New Time (hh mm ss): 070000 New Time Entered = 07:00:00 Summertime Active (Y/N)?: y SummerTime ON Accept change? (Y/N) Use number keys to enter new date and time. Date format yyyymmdd without space. Time format hhmmss without space.

Press *Enter* to confirm each change.

Press *Y* to accept change.

Calibrate clock

CDC Calibrate Clock Menu Date & Time: Thursday 2000-06-01 07:00:31 Current Calibration Factor = 0 Enter New Date (yyyy mm dd): 20010501 New Date Entered = 2001-05-01 Enter New Time (hh mm ss): 070131 New Time Entered = 07:01:31 Summertime Active (Y/N)?: y SummerTime ON Accept change? (Y/N) Use number keys to enter new date and time. Date format yyyymmdd without space. Time format hhmmss without space. Press Enter to confirm each change. Press Y to accept change. Type X to return to the previous menu or *ESC* to return to main menu.

9.9 Diagnostic Menu RD

CDC Diagnostic Menu

Press key to select function:

1: Display Digital Status IOA1

- 2: Display Digital Status IOA2
- 3: Motor Current Measurement
- 4: Brake Function
- 5: MPU Internal Status

Press the number key relating to the number in front of the desired sub menu to select.

Press *ESC* or *X* to return to main menu.

9.9.1 Digital status IOA 1

0 = Low in/output steady 1 = High in/output steady

CDC Digital Status Page IOA1

| IOA1 Input Status | | IOA1 Output Status | |
|----------------------------|---|-----------------------------|---|
| | | | |
| 2: Encoder 0-Pulse | 0 | 39:Lock Motor Pos Direction | 0 |
| 3: Encoder A-Pulse | 0 | 40:Lock Motor Neg Direction | 0 |
| 4: Encoder B-Pulse | 0 | 42:Not Used | |
| 7: Vertical Sensor PDR 1 | 1 | 44:Not Used | |
| 10:Vertical Sensor PDR 2 | 1 | 46:PDR Test | 0 |
| 12:Not Used | 0 | 48:Not Used | |
| 14:Not Used | 0 | 50:Error Signal 1 | 0 |
| 16:Slow Drive Input | 1 | 51:Door Status Output | 0 |
| 18:Stop Drive Input | 1 | | |
| 20:Not Used | 0 | | |
| 29:Safety Input (S 10) | 1 | | |
| 31:Not Used | 0 | | |
| 33:Not Used | 0 | | |
| 35:Lock In Locked Position | 0 | | |
| 37:Lock In Open Position | 1 | | |

9.9.2 Digital status IOA 2

0 = Low in/output steady1 = High in/output steady

CDC Digital Status Page IOA2

| IOA2 Input Status | | IOA |
|---------------------------|----|-----|
| | == | === |
| 2: Not Used | 0 | 39: |
| 3: Not Used | 0 | 40: |
| 4: Not Used | 0 | 42: |
| 7: High Speed Start Inner | 0 | 44: |
| 10:High Speed Start Outer | 0 | 46: |
| 12:Low Speed Start | 0 | 48: |
| 14:Lock Door Command | 0 | 50: |
| 16:Error Clear | 0 | 51: |
| 18:Auto Command | 1 | |
| 20:Key Impulse | 0 | |
| 29:Emergency Stop (E 20) | 1 | |
| 31:RotoLock Command | 0 | |
| 33:BOK Armed | 0 | |
| 35:BOK Lower Position | 0 | |
| 37:BOK Upper Position | 1 | |

| IOA2 Output Status | |
|----------------------------|---|
| | = |
| 39:BOK Motor Pos Direction | 0 |
| 40:BOK Motor Neg Direction | 0 |
| 42:BOK Magnet | 1 |
| 44:RotoLock | 0 |
| 46:BOK Motor Relay | 0 |
| 48:Not Used | |
| 50:Error Signal 2 | 1 |
| 51:General Alert | 1 |

Type *X* to return to the previous menu or *ESC* to return to main menu.

0

1

9.9.3 MPU Internal test

CDC Internal Status Page Power Fail Input 0 Evacuate Input 1

| Motor | Power | On |
|--------|-------|----|
| Lights | On | |

Power fail input

Signal from DPC indicating power failure (status code 32)(0).

Evacuate input

Signal from evacuate push button DPC J11(1).

Motor power on

Signal from MPU to DPC motor relay(0 = Door not running) (1 = Door running)

Lights on

Signal from MPU to DCP lights relay (0 = Lights off) (1 = Lights on)

9.10 Diagnostic Menu RD Access

CDC Diagnostic Menu

Press key to select function:

- 1: Display Digital Status IOA1
- 2: Display Digital Status IOA2
- 3: Display Digital Status IOB
- 4: Motor Current Measurement
- 5: Battery Status
- 6: MPU Internal Status

Press the number key relating to the number in front of the desired sub menu to select.

Press *ESC* or *X* to return to main menu.

9.10.1 Digital status IOA 1

0 = Low in/output steady1 = High in/output steady

CDC Digital Status Page IOA1

| IOA1 Input Status | | IOA1 Output Status | |
|-----------------------------|---|--------------------------|---|
| | | | |
| 2: Encoder 0-Pulse | | 39:F-wheel Motor Pos Dir | 0 |
| 3: Encoder A-Pulse | | 40:F-wheel Motor Neg Dir | 0 |
| 4: Encoder B-Pulse | | 42:Not Used | |
| 7: Vertical Sensor PDR 1 | 1 | 44:Security Level Inner | |
| 10:Vertical Sensor PDR 2 | 1 | 46:PDR Test | 1 |
| 12:System OK Inner | | 48:Not Used | |
| 14:System OK Outer | | 50:Error Signal 1 | 0 |
| 16:Slow Drive Input | 1 | 51:Door Status Output | 0 |
| 18:Stop Drive Input | 1 | | |
| 20:Freewheel released | 0 | | |
| 29:Safety Input (S 10) | 1 | | |
| 31:Freewheel Command | 0 | | |
| 33:Fire Alert Input | 1 | | |
| 35:F-wheel Motor Closed Pos | 0 | | |
| 37:F-wheel Motor Open Pos | 1 | | |

9.10.2 Digital status IOA 2

0 = Low in/output steady 1 = High in/output steady

CDC Digital Status Page IOA2

| IOA2 Input Status | |
|---------------------------|---|
| | = |
| 2: Not Used | |
| 3: Not Used | |
| 4: Mechanical Lock | 1 |
| 7: High Speed Start Inner | 0 |
| 10:High Speed Start Outer | 0 |
| 12:Low Speed Start | 0 |
| 14:Lock Door Command | 0 |
| 16:Error Clear | 0 |
| 18:Security 3 Inner | |
| 20:Security 3 Outer | |
| 29:Emergency Stop (E 20) | 1 |
| 31:Not Used | |
| 33:BOK Armed | 0 |
| 35:BOK Lower Position | 0 |
| 37:BOK Upper Position | 1 |

| IOA2 Output Status | |
|----------------------------|---|
| | = |
| 39:BOK Motor Pos Direction | 0 |
| 40:BOK Motor Neg Direction | 0 |
| 42:BOK Magnet | 1 |
| 44:Security Level Outer | |
| 46:BOK Motor Relay | 0 |
| 48:Not Used | |
| 50:Error Signal 2 | 0 |
| 51:General Alert | 0 |

Type *X* to return to the previous menu or *ESC* to return to main menu.

9.10.3 Digital status IOB

0 = Low in/output steady 1 = High in/output steady

CDC Digital Status Page IOB

| IOB Input Status | IOB Output Status | | | |
|--------------------|-------------------|---------------------------|---|--|
| | | | | |
| 1: Card Reader In | 0 | 21:Card Readre Detect In | 0 | |
| 3: Card Reader Out | 1 | 23:Card Reader Detect Out | 0 | |
| 5: Push Button In | 1 | 25:Passage Detect In | 0 | |
| 7: Push Button Out | 0 | 27:Passage Detect Out | 1 | |
| 9: Security 1 In | 0 | 29:Green Light In | 0 | |
| 11:Security 1 Out | 0 | 31:Red Light In | 0 | |
| 13:Security 2 In | 0 | 33:Green Light Out | 0 | |
| 15:Security 2 Out | 0 | 35:Red Light Out | 0 | |
| 17:Hang Sensor | 1 | 37:Vocal Message Start | 0 | |
| 19:Master Access | 0 | 39:Access Alert | 0 | |

9.11 Motor current Measurement

| CDC Mo | to | r Te | st Pag | e | | | |
|--------|----|------|--------|----|-------|----|---|
| Motor | 1 | i2t | Value | | | | 0 |
| Motor | 2 | i2t | Value | | | | 0 |
| | | | | | | | _ |
| Motor | 1 | Curi | rent | | | | 2 |
| Motor | 2 | Curi | rent | | | | 3 |
| | | | | | | | |
| | | | | | | | |
| Motor | 1 | i2t | Value | At | Error | 9A | 0 |
| Motor | 2 | i2t | Value | At | Error | 9A | 0 |

When the door is running constantly (3-3.5 rpm) the motor current value should be between 2.5 and 4.0 A. The current should be equal on motor 1 and motor 2 if a second motor is installed.

Motor i2t Value At Error 9A/D2

This value is the value that was saved when error code 9A (Motor overheated) or D2 (Motor current measure occurred. The motor with the highest value is the faulty one.

9.12 Log functions

CDC Log Menu Press key to select function: 1: Event Log Data 2: Event Log Enable Status 3: Select One Event to Print

To select operation mode, press the key relating to desired operation mode.

Press ESC or X to return to main menu.

Note No function behind 1: Reference Data and 2: Service Log.

9.12.1 Event log data

Display the 600 last events recorded in the log.

CDC Event Log Page

| 134 | Event | 10: | 2005-May-24 | 09:45:38 | ON |
|-----|-------|-----|-------------|----------|-----|
| 135 | Event | 20: | 2005-May-24 | 09:45:49 | ON |
| 136 | Event | 92: | 2005-May-24 | 09:45:53 | ON |
| 137 | Event | 83: | 2005-May-24 | 09:49:50 | ON |
| 138 | Error | 59: | 2005-May-24 | 09:52:01 | ON |
| 139 | Error | 30: | 2005-May-24 | 09:52:04 | OFF |
| 140 | Event | 77: | 2005-May-24 | 09:59:30 | ON |
| 141 | Error | 30: | 2005-May-24 | 10:00:18 | ON |
| 142 | Event | 77: | 2005-May-24 | 10:00:45 | ON |
| 143 | Event | 77: | 2005-May-24 | 10:05:52 | ON |

Type *L* to display the last 10 events in the log.

Type N to display the next 10 events in the log.

Type **P** to display the previous 10 events in the log.

Type F to display the first 10 events in the log.

Type *E* to print the entire log.

Type *W* to toggle pause on/off.

Type *S* to print selected event.

To select event to be printed type X to go to the previous menu. Select 5. Type the event to be printed e.g. 30. Press *Enter*. Type X to go to previous menu. Type 3 to return to the Event log data page and then type S.

| CDC Event | Log Enabl | .e Flags P | age 1 | | | | |
|-----------|-----------|------------|-------|-----------|-----------|-----------|-------|
| Туре | Code | Lstat | Pstat | Туре | Code | Lstat | Pstat |
| Not Used | 05 | | | Error | 57 | 1 | 1 |
| Error | 06 | 1 | 1 | Error | 58 | 1 | 1 |
| Error | 07 | 1 | 1 | Error | 59 | 1 | 1 |
| Error | 11 | 1 | 1 | Not Used | 62 | | |
| Error | 18 | 1 | 1 | Not Used | 63 | | |
| Error | 19 | 1 | 1 | Not Used | 64 | | |
| Error | 20 | 1 | 1 | Not Used | 65 | | |
| Error | 30 | 1 | 1 | Error | 71 | 1 | 1 |
| Not Used | 34 | | | Error | 72 | 1 | 1 |
| Not Used | 36 | | | Error | 73 | 1 | 1 |
| Not Used | 50 | | | Error | 74 | 1 | 1 |
| Not Used | 51 | | | Error | 75 | 1 | 1 |
| Not Used | 52 | | | Error | 76 | 1 | 1 |
| Not Used | 53 | | | Error | 9A | 1 | 1 |
| Not Used | 54 | | | Not Used | 9B | | |
| Not Used | 55 | | | Not Used | 9C | | |
| Error | 56 | 1 | 1 | Error | 9D | 1 | 1 |
| | | | | | | | |
| Lstat = L | og Enable | Status | | Pstat = P | rint Enab | le Status | |

| 9.12.2 | Event lo | g enable | status |
|--------|----------|----------|--------|
|--------|----------|----------|--------|

No value = not available

| CDC | Event | Log | Enable | Flags | Page | 2 |
|-----|-------|-----|--------|-------|------|---|
|-----|-------|-----|--------|-------|------|---|

| Туре | Code | Lstat | Pstat | Туре | Code | Lstat | Pstat |
|----------|------|-------|-------|-------|------|-------|-------|
| Error | 9F | 1 | 1 | Error | DF | 1 | 1 |
| Not Used | C1 | | | Error | ΕO | 1 | 1 |
| Error | DO | 1 | 1 | Error | E1 | 1 | 1 |
| Not Used | D1 | | | Error | E2 | 1 | 1 |
| Error | D2 | 1 | 1 | | | | |
| Not Used | D3 | | | | | | |
| Error | D4 | 1 | 1 | | | | |
| Error | D5 | 1 | 1 | | | | |
| Error | D6 | 1 | 1 | | | | |
| Error | D7 | 1 | 1 | | | | |
| Error | D8 | 1 | 1 | | | | |
| Error | D9 | 1 | 1 | | | | |
| Error | DA | 1 | 1 | | | | |
| Error | DB | 1 | 1 | | | | |
| Error | DC | 1 | 1 | | | | |
| Error | DD | 1 | 1 | | | | |
| Error | DE | 1 | 1 | | | | |

Lstat = Log Enable Status Pstat = Print Enable Status

| Tvpe | Code | Lstat | Pstat | Tvpe | Code | Lstat | Pstat |
|----------|------|-------|-------|----------|------|-------|-------|
| Status | 10 | 0 | 0 | Status | E5 | 0 | 0 |
| Not used | 12 | | | | | | |
| Status | 21 | 0 | 0 | | | | |
| Status | 22 | 0 | 0 | | | | |
| Status | 23 | | | | | | |
| Status | 25 | 0 | 0 | Event | 17 | 1 | 1 |
| Status | 26 | 0 | 0 | Not Used | 68 | | |
| Status | 29 | 0 | 0 | Event | 69 | 0 | 0 |
| Not used | 31 | | | Event | 77 | 1 | 1 |
| Not used | 32 | | | Event | 78 | 1 | 1 |
| Not used | 33 | | | Not Used | 79 | | |
| Not used | 37 | | | Event | 89 | 0 | 0 |
| Not used | AO | | | Not Used | 90 | | |
| Not used | В0 | | | Event | 99 | 1 | 1 |
| Not used | CO | | | Not Used | B1 | | |
| Status | C2 | 1 | 1 | | | | |
| Status | C3 | 1 | 1 | | | | |
| | | | | | | | |

CDC Event Log Enable Flags Page 3

Lstat = Log Enable Status Pstat = Print Enable Status

CDC Event Log Enable Flags Page 4

| Туре | Code | Lstat | Pstat | Туре | Code | Lstat | Pstat |
|-----------|-----------|--------|-------|-----------|-----------|-----------|-------|
| Mode | 81 | 0 | 0 | Impulse | 91 | 0 | 0 |
| Mode | 82 | 0 | 0 | Impulse | 92 | 0 | 0 |
| Not Used | 83 | | | Impulse | 93 | 0 | 0 |
| Not Used | 84 | | | Not Used | 94 | | |
| Not Used | 85 | | | Impulse | 95 | 0 | 0 |
| Mode | 86 | 0 | 0 | Not Used | 96 | | |
| Mode | 87 | 0 | 0 | Impulse | 97 | 0 | 0 |
| Not Used | 88 | | | | | | |
| Not Used | 8A | | | | | | |
| Mode | 98 | 0 | 0 | | | | |
| | | | | | | | |
| Lstat = L | og Enable | Status | | Pstat = P | rint Enab | le Status | |

1004466-EI-2.0

| Туре | Code | Lstat | Pstat | Туре | Code | Lstat | Pstat |
|----------|------|-------|-------|----------|------|-------|-------|
| Error | 41 | 1 | 1 | Access | A1 | 0 | 0 |
| Event | 42 | 0 | 0 | Access | A2 | 0 | 0 |
| Status | 43 | 0 | 0 | Access | A3 | 0 | 0 |
| Access | 44 | 1 | 1 | Access | A4 | 0 | 0 |
| Access | 45 | 1 | 1 | Access | A5 | 1 | 1 |
| Event | 46 | 1 | 1 | Access | A6 | 1 | 1 |
| Status | 47 | 1 | 1 | Access | A7 | 1 | 1 |
| Status | 48 | 1 | 1 | Access | A8 | 1 | 1 |
| Access | 49 | 1 | 1 | Access | A9 | 0 | 0 |
| Access | 4A | 1 | 1 | Access | AA | 0 | 0 |
| Access | 4B | 1 | 1 | Access | AB | 0 | 0 |
| Not Used | d 4C | | | Access | AC | 0 | 0 |
| Not Used | d 4D | | | Access | AD | 0 | 0 |
| Not Used | d 4E | | | Access | AE | 0 | 0 |
| Not Used | d 4F | | | Not Used | AF | | |

CDC Event Log Enable Flags Page 5

Lstat = Log Enable Status

Pstat = Print Enable Status

Type N for next page.

Type *P* for previous page.

Use *Tab*-key to select value to change.

Use number keys *1* or *0* to enter new value.

Press *Enter* to confirm each change.

Type *X* to return to the previous menu or *ESC* to return to main menu.

Description of codes (see "Code list" on page 61)

Lstat = logstatus

600 events recorded in a circular buffer

To be recorded 1=Yes, 0=No

Pstat = Printstatus

Events given printstatus 01 appear on the screen or printed on printer.

To constantly print an event with printstatus 01, set configuration option No. 20 to 1 (see "Configuration options RD" on page 79). Connect the printer to the COM port (see "Main processing unit, MPU" on page 41).

10

Real time operation

The CDC system has three different day schedules. Each day schedule may contain up to 10 different operation modes. The week schedule informs the system of which day schedule to run and in what order during a week. It is possible to make up to 16 exceptions from this week schedule for e.g. public holidays e.t.c.

10.1 Real time operation via PCD

10.1.1 Activation

Type *F556* (Real time operation ON) Prompt P3 lit's up. The door operates according to schedule.



10.1.2 Deactivation

Type *F557* (Real time operation OFF) Prompt P3 lit's down. The door operates according to manually set operation mode.

10.1.3 Key switch

Activation of the key switch (locked door command) on the PCD overrides real time operation. When the key switch is deactivated the door resume settings.



10.1.4 Manually setting of operation mode

If the door is running in real time operation mode and the operation mode is manually changed, real time operation mode is automatically deacivated. To resume real time operation mode it has to be reactivated by typing F556

10.2 Real time operation via MDT

Type *R* to toggle between real time operation ON/OFF (see "Door operation RD" on page 73).

10.3 Settings (via MDT only)

Minimum access level = 3.

CDC Real Time Operation Page DAYSCHEDULE 1 DAYSCHEDULE 2 DAYSCHEDULE 3 WEEKSCHEDULE 1 0700 LOCKED LION 0800 LOCKED LION MON DAYSCHEDULE 1 2000 LOCKED LIOF 2 0800 CONTINOUS TUE DAYSCHEDULE 1 3 0900 AUTO WED DAYSCHEDULE 1 4 1800 LOCKED LION THU DAYSCHEDULE 1 5 2200 LOCKED LIOF FRI DAYSCHEDULE 1 SAT DAYSCHEDULE 2 6 7 SUN DAYSCHEDULE 2 8 9 10 COUPDIN CONDU EVOU END כתאים

| ШΝ | SIARI EAPI | END EAPI | SCHED LN | SIARI EAPI END | EAPI SCHED | EDII FUNCTIONS |
|----|------------|------------|----------|----------------|------------|------------------|
| 1 | 2001-04-13 | 2001-04-13 | DS 2 9 | | | 1= DAYSCHEDULE 1 |
| 2 | 2001-04-16 | 2001-04-16 | DS 2 10 | | | 2= DAYSCHEDULE 2 |
| 3 | 2001-05-01 | 2001-05-01 | DS 2 11 | | | 3= DAYSCHEDULE 3 |
| 4 | 2001-05-24 | 2001-05-24 | DS 2 12 | | | 4= WEEKSCHEDULE |
| 5 | | | 13 | | | 5= EXCEPTIONS |
| 6 | | | 14 | | | |
| 7 | | | 15 | | | |
| 8 | | | 16 | | | |
| | | | | | | |

Use number key *1*, *2* or *3* to make or edit day schedule 1, 2 or 3. Use number key *4* to make or edit the week schedule.

Use number key 5 to make or edit exceptions.

10.3.1 Day schedule

```
Edit DAYSCHEDULE Menu:
     DAYSCHEDULE 1
 1
     0700 LOCKED LION
 2
     0800 CONTINOUS
     0900 AUTO
 3
 4
     1800 LOCKED LION
 5
     2200 LOCKED LIOF
 6
 7
 8
 9
10
Enter line number to edit: 4
Line entered =
                      4
Enter New Time: 2100
New Time Entered = 2100
Press SPACE to browse Mode: LOCKED LIOF
Entry Line = 4 New Time = 2100 New Mode = LOCKED LIOF Accept change? (Y/N)
                     Underlined figures are input values.
                     The different operation modes has to be in time order.
                     Use number key to select line number to make or edit.
                     Press Enter to confirm.
                     Use number key to enter time.
                     Press Enter to confirm.
                     Use space to browse between the different operation modes.
                     Available operation modes:
                     Locked Lights OFF
                     Locked Lights ON
                     LOCKED LIOF = Locked Lights OFF
                     LOCKED LION_ = Locked Lights ON
                     SECIN SECOT = Security IN and OUT
                     HSECI HSECO_ = High Security In and OUT
                     CLOIN SECOT = Closed IN Security OUT
                     HCOI HSECO = High Security losed IN, High Security OUT
                     SECIN FREOT_ = Security IN Free OUT
                     HSECI HFREO_ = High Security IN, High Free OUT
                     CLOIN FREOT = Closed IN Free OUT
                     FREIN FREOT_ = Free IN Free OUT
                     Clear entry (to erase the event from the day schedule)
                     Press Enter to confirm
                     Type Y or N to accept or not accept changes.
                     Type X to return to the previous menu or ESC to return to main menu.
```



```
Edit WEEKSCHEDULE Menu:

WEEKSCHEDULE 1

1 MON DAYSCHEDULE 1

2 TUE DAYSCHEDULE 1

3 WED DAYSCHEDULE 1

4 THU DAYSCHEDULE 1

5 FRI DAYSCHEDULE 1

6 SAT DAYSCHEDULE 2

7 SUN DAYSCHEDULE 3

Enter line number to edit: 7

Line entered = 7

Enter New Day Schedule (1-3): 3

New Day Schedule Entered = 3

Line 7 DAYSCHEDULE 3
```

Accept change? (Y/N)

Underlined figures are input values.

Use number key to select line number to make or edit.

Press *Enter* to confirm.

Use number key to enter day schedule.

Press Enter to confirm.

Type *Y* or *N* to accept or not accept changes.

10.3.3 Exceptions

Edit EXCEPTIONS Menu: START EXPT LN END EXPT SCHED LN START EXPT END EXPT SCHED 2001-04-13 1 2001-04-13 DS 2 9 2 2001-04-16 2001-04-06 DS 2 10 2001-05-01 2001-05-01 3 DS 2 11 4 2001-05-24 2001-05-24 DS 2 12 5 13 6 14 7 15 8 16 Enter line number to edit: 5 Line entered = 5 Enter New Start Time (yyyy mm dd): 20011224 New Start Time Entered =2001-12-24 Enter New End Time (yyyy mm dd): 20011224 New End Time Entered = 2001-12-24 Enter New Exception Schedule (1-3): 2 New Exception Entered = 2 Line 5 Start Time = 2001-12-24 End Time = 2001-12-24 DAYSCHEDULE 2 Accept change? (Y/N)

Underlined figures are input values.

Use number key to select line number to make or edit.

Press Enter to confirm.

Use number key to enter start date.

Date format yyyymmdd without space.

Press *Enter* to confirm.

Use number key to enter end date.

Date format yyyymmdd without space.

Press Enter to confirm.

Use number key to select day schedule.

Press Enter to confirm

Type *Y* or *N* to accept or not accept changes.

Remote Control Operation

11.1 Connection

To enable remote control of the CDC system a telephone modem is connected to the COM port on the CDC-unit. The modem is then connected either to a cellular phone or to the common telephone line to establish contact with a VT100 -terminal or a PC placed elsewhere.



11.2 Operation

Remote control operation is performed the same way as operation via an MDT (see "Main Diagnostic Terminal MDT, operation" on page 66).

Cable from Mpu to Modem/ GSM



12

12.1 Cut out for PCD/Reception plate



Cable 2 x 8 x 0.25 mm² LIYCY and alternative Cable 2 x UTP CAT5

12.2 Spotlights





Colour temp. 3050 K Lifetime 3000 hours Lamp 20 W

12.3 Downlights





Colour temp. 3000 K Lifetime 10000 hours Lamp 18 W

12.4 Water resistant roof



| Item | Description |
|------|--------------------------------|
| А | Water outlet |
| В | Aluminium extrusion (16x20 mm) |
| С | Roofing rubber |
| D | Wooden beam |

12.5 Activator PIR



12.5.1 Mechanical installation:

Mount the PIR-30 attachment on the wall ring above the inside and the outside openings.

12.5.2 Electrical connections



| Connection | Colour | | Voltage |
|------------|------------------------|-----------------|-----------|
| 1 | White | - | 12-30VDC |
| 2 | Brown | + | 12-24 VAC |
| 3 | Green | Common | 48 VAC/DC |
| 4 | 4 Yellow Normally open | | 30W/60VA |
| 5 | Grey | Normally closed | |

12.5.3 Adjustment PIR-30.



Pot. A Sensitivity of the sensor system (min=0 and max=10).



Sideways adjustment.

Three scanning pattern graduations for coverage of the lateral zones 1-3. (Lenses which are covered by slides are inactivated).





സ

Frontal adjustment

Frontal slides, for adjustment of scanning depth C-A.



Frontal adjustment by swivelling the unit by graduations of 5°. For shifting along the depth of the entire scanning field.

12.5.4 Replacing PIR-30



Replacing PIR-30

When replacing a used PIR, it is normally not necessary to replace the housing and cabling, only the PC-board.

Do as follows:

- 1. Remove the front cover A (can be made from "the outside" without taking down the fascia sheets).
- 2. Remove the slider frame B.
- 3. Pull out the PC board C and disconnect the wires D and replace the PC-board.
- 4. When reassembling make sure that the LED and the LED window (A) are located at the right top corner of the PIR.



12.6 Activator DSR



The DSR is factory preset for the RD3/4. The settings of the DSR can be made with a remote control device.

Mechanical installation:

Mount the DSR on the wall ring according to picture above with the cable outlet to the right. Put the foam in with the white side facing the activator.

The picture is shown facing the door.

Electrical connection



12.6.1 Adjustment of sensitivity



Sensitivity 0 - 9. Default setting 7.

To change the sensitivity press the marked + or - to increase or decrease the sensitivity. One push changes the sensitivity one step.

12.7 Emergency stop button



Electrical connection (see "IOA 2-board" on page 45).

12.8 Push button for disabled

Connect the push buttons to the inner/outer low speed impulse on the IOA 2board (see "IOA 2-board" on page 45).





12.9 Emergency opening button



Electrical connection according to connection diagram.

12.10 Compressible safety switches



Electrical connection according to connection diagram.

12.11 Eye-Tech

Electrical connection according to connection diagram.



12.12 Vertical PDR



Range

Check the range of the detection zone by moving a test body (diameter. 50mm) downwards along the vertical rubber edge.

The PDR should be activated at a distance of 1.5 m from the floor.

The detection zone ends about 50-80 mm from the floor.

The length of the detection zone can be adjusted with the screw (A) located behind the cover. Turning the screw clockwise gives a longer detection zone.





Electromechanical lock 12.13



Mount the electromechanical lock on the drive units mounting plate. Position A - 4-wing doors. Position B - 3-wing doors.

Rotation lock 12.14



Electrical connection according to connection diagram.

12.15 Fixed screen joint section




12.16 Insulated fascia



12.17 Ground ring



The kit consists of:

- 2 No. 180° ring parts
- 6 No. Spokes
- 7 No. Supports
- 6 No. Screws M6S 12x20
- 8 No. Nuts M6M 12
- 12 No. Screws RTS ST 6.3x19



- 1. Screw the two 180° ring parts together.
- 2. Mount the spokes and the supports.
- 3. Put the ground ring in its correct position.
- 4. Check the roundness of the ground ring.
- 5. Level the ground ring to its correct height by adjusting the supports.
- 6. Fix the ground ring to the floor.
- 7. If necessary, cut the threaded rod on the supports.





Electrical connection according to connection diagram



12.19 Modem options





12.20 Hang sensor



Put the drive shaft (A) on top of the central floor disc (B). Make sure that the guide (C) slides in the adjacent hole.

Mount the drive shaft to the gear wheel.

Mount the micro switch (D) on the encoder bracket.

Adjust the screw (E) so the micro switch just close.

Mount the door leaves.

Connect a test buzzer to the connector.

Put an allen key through the 9 mm adjustment hole (G) into one of the slots in the adjustment nut (H).

Turn the drive shaft and door leaves clockwise until the micro switch open plus two extra turns.

Adjust the adjust screw (E) so it just touch the micro switch. Secure the screw with the nut (F).

Check the function and adjust the weight necessary to activate the hang sensor if necessary.

Put an allen key through the 9 mm adjustment hole (G) into one of the slots in the adjustment nut (H).

To increase the weight, turn the drive shaft and door leaves clockwise.

To decrease the weight, turn the drive shaft and door leaves counter clockwise.

Disconnect the test buzzer.

Electrical connection according to connection diagram.

12.21 ROM-corder



- 1. Microphone
- 2. Selecting switch
- 3. Volume control
- 4. Start button message 1
- 5. Start button message 2
- 6. Terminal

| Connection | Description |
|------------|---|
| 1 | Power supply + 24V DC |
| 2 | Power supply - 24V DC |
| 3 | Start message 1 + |
| 4 | Start message 1 - |
| 5 | Start message 2 + |
| 6 | Start message 2 - |
| 7, 8 | Loud speaker 1 (8¾) |
| 9, 10 | Loud speaker 2 (8 ³ / ₄) |

12.21.1 Recording message 1

- 1. Put the "select switch (2)" in position RECORD.
- 2. Press and hold down "start button message 1 (4)".
- 3. Speak into the microphone (1) from a distance of approximately 100mm, and clearly state Your message. The message can be up to 60 seconds long.
- 4. Release "start button message 1 (4)".
- 5. To record message 2 use the same procedure as for message 1, but instead of pressing and holding down "start button message 1 (4)" press and hold down "start button message 2 (5)"

12.21.2 Play message 1

- 1. Put the "select switch (2)" in position PLAY.
- 2. To check the recorded message 1, press "start button message 1 (4)".
- 3. For remote start of message 1 put a voltage between connection 3 and 4 on the terminal (6).

To check the recorded message 2, press "start button message 2 (5)".

For remote start of message 2 put a voltage between connection 5 and 6 on the terminal (6).

The volume of the played message can be adjusted with the "volume control (3)".

This unit has a battery back up. This means that a message can be recorded without having the unit connected to the power supply, but the recorded message can not be checked or remote started without connection to the power supply (connection 1 and 2 on the terminal).

- Speed settings of the door according to "STI 04-014 Revolving doors safety instructions"
- Handicap speed settings

If the door is equipped with brake-out kit, the function must be tested. Put grease on pins that hold door leaves.

If door are equipped with optional safety the function of these must be tested.

Drive unit and transmission

- Bolt connections, frame
- Carbon motor
- Belt tension
- Motor attachment
- No abnormal sound, motor
- No abnormal sound gearbox



• Check the adjustment of the drive belt, using the belt tightener tool (B) (part No. 248385).

The procedure for adjusting the belt is described in FI 009. When a force of app. 20N is applied to the belt, the deviation shall be approx. 3 mm.

• Check the cables.



- Check the commutator brushes. Minimum length 7.5 mm.
- Clean the commutator

Emergency stop, function

- Stop button 1
- Stop button 2

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